University Course

# EGEE 518 Digital Signal Processing I

California State University, Fullerton Fall 2008

 $\label{eq:My Class Notes} {\bf My \ Class \ Notes} \\ {\bf Nasser \ M. \ Abbasi}$ 

Fall 2008

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| 4 | HWs         4.1       HW2         4.2       HW3         4.3       HW4, Some floating points computation         4.4       HW5 | 7<br>7<br>14<br>30<br>40 |

# introduction

I took this course in Fall 2008 at CSUF to learn more about DSP.

This course was hard. The textbook was not too easy, The instructor Dr Shiva has tremendous experience in this subject, and he would explain some difficult things with examples on the board which helped quite a bit. The final exam was hard, it was 7 questions and I had no time to finish them all. It is a very useful course to take to learn about signal processing.

#### DIGITAL SIGNAL PROCESSING (CLOTH)



Instructor is professor Shiva, Mostaf, Dept Chair, EE, CSUF.



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# Final project

final project

# Study notes

### 3.1 DSP notes

For fourier transform in mathematica, use these options

```
ln[8]:= FourierTransform[1, t, s, FourierParameters \rightarrow \{-1, 1\}]
Out[8]= DiracDelta[s]
```

From Wikipedia. Discrete convolution

#### Discrete convolution

edit

For complex-valued functions *f*, *g* defined on the set of integers, the **discrete convolution** of *f* and *g* is given but

$$\begin{split} f * g)[n] &\stackrel{\text{def}}{=} \sum_{\substack{m=-\infty\\\infty\\m=-\infty}}^{\infty} f[m] \cdot g[n-m] \\ &= \sum_{m=-\infty}^{\infty} f[n-m] \cdot g[m]. \quad \text{(commutativity)} \end{split}$$

Autocorrelaton

energy. Signals that "last forever" are treated instead as random processes, in which case different definitions are needed, based on expected values. For wide-sense-stationary random processes, the autocorrelations are defined as

$$R_{ff}(\tau) = \mathbb{E}\left[f(t)\overline{f}(t-\tau)\right]$$
$$R_{xx}(j) = \mathbb{E}\left[x_n\overline{x}_{n-j}\right].$$

For processes that are not stationary, these will also be functions of t, or n.

For processes that are also ergodic, the expectation can be replaced by the limit of a time average. The autocorrelation of an ergodic process is sometimes defined as or equated to<sup>[3]</sup>

$$R_{ff}(\tau) = \lim_{T \to \infty} \frac{1}{T} \int_0^T f(t+\tau)\overline{f}(t) dt$$
$$R_{xx}(j) = \lim_{N \to \infty} \frac{1}{N} \sum_{n=0}^{N-1} x_n \overline{x}_{n-j}.$$

These definitions have the advantage that they give sensible well-defined single-parameter results for periodic functions, even when those functions are not the output of stationary ergodic processes.

<sup>1</sup> function nma\_show\_fourier

 $<sup>\</sup>mathbf{2}$ 

<sup>3</sup> t=-4:.1:4;

<sup>4</sup> N=4;

<sup>5</sup> T=2;

```
6
   plot(t,y(t,-N,N,T));
7
8
9
    \quad \text{end} \quad
10
    %-----
11
   function v=c(k,T)
12
    term=pi*k/2;
13
    v=(1/T)*sin(term)/term;
14
    end
15
16
   %-----
17
   function v=y(t,from,to,T)
18
19
20
    coeff=zeros(to-from+1,1);
21 k=0;
22 for i=from:to
       k=k+1;
23
        coeff(k)=c(i,T);
24
    end
25
26
    v=zeros(length(t),1);
27
    for i=1:length(t)
28
29
        v(i)=0;
        for k=from:to
30
31
             v(i)=v(i)+coeff(k)*exp(sqrt(-1)*2*pi/T*k*t(i));
        \quad \text{end} \quad
32
33
    end
34
    \quad \text{end} \quad
```

## $\mathbf{HWs}$

### 4.1 HW2

#### Local contents

| 4.1.1 | Problem 1   | <br> |       |   |   |   |  |  |   |  |       |   |   |   |  |   |  |   |   | 7  |
|-------|-------------|------|-------|---|---|---|--|--|---|--|-------|---|---|---|--|---|--|---|---|----|
| 4.1.2 | Problem $2$ | <br> |       |   |   |   |  |  | • |  |       | • |   |   |  |   |  | • | • | 8  |
| 4.1.3 | graded HW2  | <br> | <br>• | • | • | • |  |  | • |  | <br>• | • | • | • |  | • |  | • | • | 10 |

#### 4.1.1 Problem 1

Compute an appropriate sampling rate and DFT size  $N = 2^v$  to analyze a single with no significant frequency content above 10khz and with a minimum resolution of 100 hz

#### 4.1.1.1 Solution

From Nyquist sampling theory we obtain that sampling frequency is

$$f_s = 20000 \ hz$$

Now, the frequency resolution is given by

$$\Delta f = \frac{f_s}{N}$$

where N is the number of FFT samples. Now since the minimum  $\Delta f$  is 100 hz then we write

$$\frac{f_s}{N} = \Delta f \ge 100$$

or

$$\frac{f_s}{N} \ge 100$$

Hence

$$N \le \frac{20,000}{100} \le 200 \text{ samples}$$

Therefore, we need the closest N below 200 which is power of 2, and hence

$$N = 128$$

#### 4.1.2 Problem 2

sketch the locus of points obtained using Chirp Z Transform in the Z plane for  $M=8, W_0=2, \phi_0=\frac{\pi}{16}, A_0=2, \theta_0=\frac{\pi}{4}$ 

#### Answer:

Chirp Z transform is defined as

$$X(z_k) = \sum_{n=0}^{N-1} x[n] z_k^{-n} \qquad k = 0, 1, \cdots, M-1$$
(1)

Where

$$z_k = AW^{-k}$$

and  $A = A_0 e^{j\theta_0}$  and  $W = W_0 e^{-j\phi_0}$ 

Hence

$$z_k = \left(A_0 e^{j\theta_0}\right) \left(W_0 e^{-j\phi_0}\right)^{-k}$$
$$= \frac{A_0}{W_0^k} e^{j(\theta_0 + k\phi_0)}$$

Hence

$$|z_k| = \frac{A_0}{W_0^k}$$
$$= \frac{2}{2^k}$$

and

phase of 
$$z_k = \theta_0 + k\phi_0$$
  
=  $\frac{\pi}{4} + k\frac{\pi}{16}$ 

Hence

| k | $ z_k  = \frac{2}{2^k}$        | <i>phase of</i> $z_k = \frac{\pi}{4} + k \frac{\pi}{16}$     | phase of $z_k$ in degrees |
|---|--------------------------------|--|---------------------------|
| 0 | $\frac{2}{1} = 2$              | $\frac{\pi}{4} + 0 \times \frac{\pi}{16} = \frac{\pi}{4}$    | 45                        |
| 1 | $\frac{2}{2} = 1$              | $\frac{\pi}{4} + 1 \times \frac{\pi}{16} = \frac{5}{16}\pi$  | 56.25                     |
| 2 | $\frac{2}{4} = \frac{1}{2}$    | $\frac{\pi}{4} + 2 \times \frac{\pi}{16} = \frac{3}{8}\pi$   | 67.5                      |
| 3 | $\frac{2}{8} = \frac{1}{4}$    | $\frac{\pi}{4} + 3 \times \frac{\pi}{16} = \frac{7}{16}\pi$  | 78.75                     |
| 4 | $\frac{2}{16} = \frac{1}{8}$   | $\frac{\pi}{4} + 4 \times \frac{\pi}{16} = \frac{1}{2}\pi$   | 90                        |
| 5 | $\frac{2}{32} = \frac{1}{16}$  | $\frac{\pi}{4} + 5 \times \frac{\pi}{16} = \frac{9}{16}\pi$  | 101.25                    |
| 6 | $\frac{2}{64} = \frac{1}{32}$  | $\frac{\pi}{4} + 6 \times \frac{\pi}{16} = \frac{5}{8}\pi$   | 112.5                     |
| 7 | $\frac{2}{128} = \frac{1}{64}$ | $\frac{\pi}{4} + 7 \times \frac{\pi}{16} = \frac{11}{16}\pi$ | 123.75                    |



Figure 4.1: plot of the above contour

This is Mathematica notebook used to make plot of the Chirp Z transform contour. This is my graded HW2

## 4.1.3 graded HW2



#### 1 Problem 1

Compute an appropriate sampling rate and DFT size  $N = 2^v$  to analyze a single with no significant frequency content above 10khz and with a minimum resolution of 100hz

#### Solution

From Nyquist sampling theory we obtain that sampling frequency is

 $f_s = 20000 \ hz$ 

Now, the frequency resolution is given by

$$\Delta f = \frac{f_s}{N}$$

where N is the number of FFT samples. Now since the minimum  $\Delta f$  is 100 hz then we write

$$\frac{f_s}{N} = \Delta f \ge 100$$

or

$$\frac{f_s}{N} \ge 100$$

Hence

$$\frac{20,000}{100} \le 200 \text{ samples}$$

1

Therefore, we need the closest N below 200 which is power of 2, and hence

$$\frac{N=128}{5}$$

4 2 Problem 2  $\frac{\pi}{16}, A_0 = 2, \theta_0 = \frac{\pi}{4}$ Answer: Chirp Z transform is defined as λ Where and  $A = A_0 e^{j\theta_0}$  and  $W = W_0 e^{-j\phi_0}$ Hence Hence

$$|z_k| = \frac{A_0}{W_0^k}$$
$$= \frac{2}{2^k}$$

 $z_{k} = (A_{0}e^{j\theta_{0}}) (W_{0}e^{-j\phi_{0}})^{-k}$  $= \frac{A_{0}}{W_{0}^{k}}e^{j(\theta_{0}+k\phi_{0})}$ 

and

phase of  $z_k = \theta_0 + k\phi_0$ =  $\frac{\pi}{4} + k\frac{\pi}{16}$ 

Hence

| k | $ z_k  = \frac{2}{2^k}$        | phase of $z_k = \frac{\pi}{4} + k\frac{\pi}{16}$             | phase of $z_k$ in degrees |
|---|--------------------------------|--|---------------------------|
| 0 | $\frac{2}{1} = 2$              | $\frac{\pi}{4} + 0 \times \frac{\pi}{16} = \frac{\pi}{4}$    | 45                        |
| 1 | $\frac{2}{2} = 1$              | $\frac{\pi}{4} + 1 \times \frac{\pi}{16} = \frac{5}{16}\pi$  | 56.25                     |
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| 3 | $\frac{2}{8} = \frac{1}{4}$    | $\frac{\pi}{4} + 3 \times \frac{\pi}{16} = \frac{7}{16}\pi$  | 78.75                     |
| 4 | $\frac{2}{16} = \frac{1}{8}$   | $\frac{\pi}{4} + 4 \times \frac{\pi}{16} = \frac{1}{2}\pi$   | 90                        |
| 5 | $\frac{2}{32} = \frac{1}{16}$  | $\frac{\pi}{4} + 5 \times \frac{\pi}{16} = \frac{9}{16}\pi$  | 101.25                    |
| 6 | $\frac{2}{64} = \frac{1}{32}$  | $\frac{\pi}{4} + 6 \times \frac{\pi}{16} = \frac{5}{8}\pi$   | 112.5                     |
| 7 | $\frac{2}{128} = \frac{1}{64}$ | $\frac{\pi}{4} + 7 \times \frac{\pi}{16} = \frac{11}{16}\pi$ | 123.75                    |

2

sketch the locus of points obtained using Chirp Z Transform in the Z plane for  $M = 8, W_0 = 2, \phi_0 =$ 

 $z_k = AW^{-k}$ 

$$X(z_k) = \sum_{n=0}^{N-1} x[n] z_k^{-n} \qquad k = 0, 1, \cdots, M-1$$
(1)



### 4.2 HW3

| Local | contents     |  |  |  |  |  |  |  |   |   |   |   |   |   |  |   |   |   |  |    |
|-------|--------------|--|--|--|--|--|--|--|---|---|---|---|---|---|--|---|---|---|--|----|
| 4.2.1 | my solution  |  |  |  |  |  |  |  |   | • | • |   |   | • |  | • |   |   |  | 14 |
| 4.2.2 | key solution |  |  |  |  |  |  |  | • | • | • | • | • | • |  | • | • | • |  | 23 |

#### 4.2.1 my solution

 $\mathcal{O}$ Definitions Danto Correlation Rxx(N, N+m); Measurers the similarity of R.P. X(t) at time n and X(t) at later time NEM.  $R_{XX}(n,n+m) = E \{X(n) \mid X(n+m)\}$ 2 stationary process. This is a random process whose statistics do not change with shift in time origin. 3 Wide Sense Stationay process: This is a random process X(+) which statistic the following Conditions : its mean is Constant. i.e E[X] = Constant. 1. 2. auto correlation depends only on time intervel m.  $\mathcal{R}_{xx}\left(n,n+m\right)=\mathcal{R}_{xx}\left(m\right).$ 1.e notice that stationary process is WSS, but WSS is not heccessory Stationage in WSS (4) Time averageo, Ensemble averages Time averages is the average of the Sample sequence. While Ensemble average is statistical mean. X(tn) in R.V. simple 1 . En time average is < Sample 1 - Sample 2 man sample 3 太io event· Stime tin conserve de aurase is E[X(tn)]

Ð 5 white Noise; this is a R.P. whose power spectral density is constant. i.e. power contained is a frequency bandwidth B is the same regadless of while this bandwidth is contored. 1/2(0)/ "-flat" spectrum implies X(4) is white Noise process. ⇒س the above is a description in the frequency domain. in the time domain,  $\Phi_{XX}(m) = S(m)$  in the autocorrelation is nonzero only if this unternal is Zero. i.e X(+) only correlated with itself at Zer trine delay. So all R.V. that kelong to a white noise process are unconcluted with each others is time interval is nonzero. (6) Erogolic Process; this is a R.D. when statistic taken from the time samples are the same as statistics taken from Ensembles. for example. We say a process is Ergodic in the mean, then E{X(t)] = <X(t)> Atatiscal sample. expected value of time average. mean of a sample (or time R.V. series) the above equality to in the limit, i.e as the time series length increases. and the statiscal mean is when the Number of time series Increase as well.

$$\frac{1}{4} \cdot 4 \quad |et e(h) while Noise Sequence. Let s(h) unconditied 
Sequence to  $C(h)$ . Show that  $y(h) = S(h) e(h)$  is  
while. The  $E[y(h) y(h+h)] = A S(h)$ .  

$$\frac{dhswai}{E[y(h) y(h+h)]} = E[S(h)e(h) S(h+h)e(h+h)]$$

$$= E[S(h)S(h+h)] C(h)e(h+h)]$$
Since  $e(h)$  and  $S(h)$  are uncorrectived, hence independent, thus  
we can write the show as  

$$= E[S(h)S(h+h)] = E[S(h)e(h+h)] = [S(h)] = \frac{1}{2} \frac{1}{$$$$

(c) 
$$B_{XX}(w) = E \{X(x), X(u+w)\} = E \{X_{n+m}^{*}, X_{n}\} = \left(E \{X_{n+m}^{*}, X_{n}\}\} = \Phi_{XX}^{*}(-w)\right)$$
  
if process is real, thus  $\Phi_{XX}^{*}(-w) = \Phi_{XX}(-w)$ .  
if  $Process is real, thus  $\Phi_{XX}^{*}(-w) = \Phi_{XX}(-w)$ .  
if  $Process is real, thus  $\Phi_{XX}^{*}(-w) = \Phi_{XX}(-w)$ .  
if  $Process is real, thus  $\Phi_{XX}^{*}(-w) = \Phi_{XX}(-w)$ .  
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 $= \Phi_{XX}^{*}(w) = \Phi_{XX}(-w)$ .  
 $= \Phi_{XX}^{*}(w) = h_{XX}w_{X}^{*}$ .  
 $= \Phi_{XX}^{*}(-w) = h_{XX}w_{X}^{*}$ .  
 $= e \{X_{n+m}, X_{n}\} = h_{XX}(-w)$ .  
 $= e \{X_{n+m}, X_{n}\} = h_{XX}(-w) = h_{XX}(-w)$ .  
 $= e \{X_{n+m}, X_{n}\} = h_{XX}(-w) = h_{XX}(-w)$ .  
 $= e \{X_{n+m}, Y_{n}\} = h_{XX}(-w) = h_{XX}(-w)$ .  
 $= e \{X_{n+m}, Y_{n}\} = h_{XX}(-w) = h_{XX}(-w) = h_{XX}(-w)$ .  
 $= e \{X_{n+m}, Y_{n}\} = h_{XX}(-w) = h_{XX}(-w) = h_{XX}(-w)$ .  
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 $= e \{(h_{n}) \times (h_{n})\} = h_{XX}(-w) = h_{XX}(-w) = h_{XX}(-w)$ .  
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 $= e \{(h_{N}) \times (h_{N})\} = h_{XX}(-w) = h_{XX}(-w)$ .  
 $= e \{(h_{N})$$$$$ 

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$$\frac{1}{2} \frac{p_{xy}(1-q)}{p_{xy}(1-q)} \leq \left( \frac{p_{xx}(q)}{p_{xx}(q)} + \frac{q_{yy}(q)}{p_{yy}(q)} \right)$$

$$\frac{1}{2} \frac{p_{xy}(1-q)}{p_{xy}(q)} = E \sum_{x=1}^{2} \frac{q_{x=1}^{2}}{p_{x=1}^{2}}$$

$$\frac{1}{2} \frac{p_{yy}(q)}{p_{yy}(q)} = E \sum_{x=1}^{2} \frac{q_{x=1}^{2}}{p_{x=1}^{2}}$$

$$\frac{1}{2} \frac{p_{xx}(q)}{p_{xx}(q)} = E \sum_{x=1}^{2} \frac{q_{x=1}^{2}}{p_{x}^{2}}$$

$$\frac{1}{2} \frac{p_{xx}(q)}{p_{xx}(q)} = E \sum_{x=1}^{2} \frac{q_{x}^{2}}{p_{xx}^{2}} + \frac{q_{x}^{2}}{q_{xx}(q)} + \frac{q_{x}^{2}}{p_{xx}^{2}} + \frac{q_{x}^{2}}{q_{xx}(q)} + \frac{q_{x}^{2}}{p_{x}^{2}} + \frac{q_{x}^{2}}{q_{xx}(q)} + \frac{q_{x}^{2}}{p_{x}^{2}} + \frac{q_{x}^{2}}{q_{xx}(q)} + \frac{q_{x}^{2}}{p_{x}^{2}} + \frac{q_{x}^{2}}{q_{xx}(q)} + \frac{q_{x}^{2}}{p_{x}^{2}} + \frac{q_{x}^{2}}{p_{xx}(q)} + \frac{q_{x}^{2}}{p_{x}^{2}} + \frac{q_{x}^{2}}{p_{xx}(q)} + \frac{q_{x}^{2}}{p_{x}^{2}} + \frac{q_{x}^{2}}{p_{xy}(q)} + \frac{q_{x}^{2}}{p_{x}^{2}} +$$

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## 4.2.2 key solution

H.W. # 3 Sol.  
() a) Autocorrelation registence : 
$$\oint_{X_X} (h_{3,M})$$
 is  
refined ly  
 $\oint_{X_0} (n_{3,M}) = E \{X_n X_m^*\} = \iint_{X_n X_m} P_{X_n X_m} (X_{n-2}n, X_m, m) dX_n d\}$   
b) A random process  $\{X_n\}$  is a stationary process if  
its statistics are not affected ling a shift in the  
time origin . i.e.,  $X_n$  and  $X_m$  have the same  
statistic for all n and m  
c) A stationary random process in the undersemean  
(i) The mean is constant  
(ii) the autocorrelation ( $z^{nd}$  order statistics) depend  
only on the time difference hetween the random  
wariables  
defined as  
 $\langle X_n \rangle = lim \frac{1}{2N+1} \sum_{n=-N}^{N} X_n$   
Ensemble average of a random process  $\{X_n\}$  is  
defined as  
 $M_{X_n} = E \{X_n\} = \int_{-\infty}^{\infty} P_{X_n}(X_{3,n}) dX$ 

23

$$\begin{split} h) For truncation \\ m_{e} &= \frac{1}{\Delta} \int_{-\Delta}^{0} e \quad de = \frac{1}{\Delta} \frac{e^{2}}{2} \Big|_{-\Delta}^{0} = -\frac{\Delta}{2} \\ \frac{\nabla e^{2}}{2} &= E \left\{ (e_{n} + \frac{\Delta}{2})^{2} \right\} = E \left\{ e_{n}^{2} \right\} + \frac{\Delta^{2}}{4} + 2\frac{\Delta}{2} E \left\{ e_{n} \right\} \\ &= E \left\{ e_{n}^{2} \right\} + \frac{\Delta^{2}}{4} - \frac{\Delta^{2}}{2} = E \left\{ e_{n}^{2} \right\} - \frac{\Delta^{2}}{4} \\ \nabla e^{2} &= \frac{1}{\Delta} \int_{-\Delta}^{0} e^{2} de - \frac{\Delta^{2}}{4} = \frac{1}{\Delta} \frac{e^{3}}{3} \Big|_{-\Delta}^{0} - \frac{\Delta^{2}}{4} = \frac{\Delta}{12} \\ \hline (3) \quad \frac{8 \cdot 4}{-\Delta} \quad e(n) : \text{ undife morie neg.} \\ &= S(n) : \text{ uncorrelated with en} \\ &= S \wedge ow \quad Y(n) = S(n) e(n) \quad in \text{ undife : } p(i.e. \\ &= \left\{ Y(n) Y(n+m) \right\} = A \quad S(m) \\ &= \frac{1}{\Delta} \cos n t. \\ &= \left\{ Y(n) Y(n+m) \right\} = F \left\{ e(n) e(n+m) \right\} = \nabla e^{2} \quad S(m) \\ &= \frac{1}{\Delta} \cos n t. \\ &= \left\{ Y(n) Y(n+m) \right\} = E \left\{ s(n) e(n) \quad S(n+m) e(n+m) \right\} \\ &= E \left\{ Y(n) Y(n+m) \right\} = E \left\{ s(n) S(n+m) e(n+m) \right\} \\ &= E \left\{ S(n) S(n+m) \right\} = E \left\{ e(n) e(n+m) \right\} \\ &= E \left\{ S(n) S(n+m) \right\} = E \left\{ e(n) e(n+m) \right\} \\ &= E \left\{ S(n) S(n+m) \right\} = E \left\{ e(n) e(n+m) \right\} \\ &= \nabla s^{2} \quad \nabla e^{2} \quad S(m) \\ &= \nabla s^{2} \quad \nabla e^{2} \quad S(m) \end{aligned}$$

t

Consider the two real stationary random processes { xn } and ها.8 (yn }. with means mx and my and variances of 2 and of 2. show the following  $4 V_{xy}(m) = \Phi_{xy}(m) - m_x - m_y$ (a)  $\delta_{xx}(m) = \phi_{xx}(m) - m_{x}^{2}$  $\delta'_{xx}$  (m) = E[ (x<sub>n</sub>-m<sub>x</sub>)(x<sub>n+m</sub>-m<sub>x</sub>)] = E[ x<sub>n</sub> x<sub>ntm</sub>]-m<sub>x</sub> E[ x<sub>ntm</sub>]-m<sub>x</sub> E[ x<sub>n</sub>]+m<sub>x</sub>m<sub>x</sub>  $= \mathscr{G}_{XX}(m) - m_{x} m_{x} - m_{x} m_{x} + m_{x} m_{x}$  $= \phi_{XX}(m) - m_X^2$  $\delta'_{xy}(m) = E\left[(x_n - m_x)(y_{n+m} - m_y)\right]$ = E[ xn yn+m]-mxmy-mymx+mxmy = \$ xy (m) - mx my  $(b)_{\frac{\varphi_{XX}(0)}{\varphi_{XY}(m)} = E[x_n x_{n+m}]^{2}} \frac{\partial}{\partial x_{XX}(0)} = \nabla \overline{x}^{2}$  $\beta_{XY}(o) = E[x_n x_n] = mean square$  $\delta_{xx}(m) = E\left[(x_n - m_x)(x_{n+m} - m_x)\right]$  $\delta_{XX}(o) = E\left[\left(X_{n}-m_{X}\right)^{2}\right] = \sigma_{X}^{2}$ (c)  $\phi_{xx}$  (m) =  $\phi_{xx}$  (-m)  $\phi_{xy}(-m) = (E[x_n x_{n-m}])$ let n'= n-m  $\emptyset_{xx}(-m) = (E[x_{n'xm}, x_{n'}]) = E[x_{n'}, x_{n'+m}]$  $= \phi_{xx}(m)$  $\delta_{\chi\chi}(m) = \delta_{\chi\chi}(-m)$  $\delta_{xx}^{*}(-m) = \left( E \left[ (x_{n} - m_{x})(x_{n-m} - m_{x}) \right] \right)$ =  $(E[(x_{n'+m}-m_{k})(x_{n'}-m_{k})])$ =  $E[(x_{n'} - m_{k})(x_{n'+m} - m_{k})]$ = 8 xx (m) 

$$\frac{\mathcal{J}_{sy}(m) : \mathcal{J}_{sy}(m)}{\mathcal{J}_{sy}(m) : (\mathcal{L}_{sy}(m) - m_{y})(x_{nm} - m_{y})]} = (\mathcal{L}[(y_{n}, -m_{y})(x_{n}, -m_{y})])$$

$$= \mathcal{L}[(x_{n}, -m_{y})(y_{n}, -m_{y})]$$

$$= \mathcal{L}[(x_{n}, -m_{y})(y_{n}, -m_{y})]$$

$$= \mathcal{J}_{sy}(m)$$

$$\frac{\mathcal{J}_{sy}(m) : (\mathcal{L}[(y_{n}, -m_{y})(x_{n}, -m_{y})])}{\mathcal{J}_{sy}(m) : (\mathcal{L}[(y_{n}, -m_{y})(y_{n}, -m_{y})])}$$

$$= \mathcal{L}[(x_{n}, -m_{y})(y_{n}, -m_{y})]$$

$$= \mathcal{L}[(x_{n}, -m_{y})(x_{n}, -m_{y})]$$

$$= \mathcal{L}[(x_{n}, -m_{y$$

$$\begin{bmatrix} \begin{bmatrix} y_{x_{1}}(x) & y_{y_{1}}(x) \end{bmatrix}^{\frac{1}{2}} \ge \int_{x_{2}} (y_{x_{1}}(y_{1}) \\ \end{bmatrix}$$
Letting  $\frac{1}{2} = x_{n}$  we can obtaining there is inequalities to
$$\begin{bmatrix} \frac{1}{2} \frac{y_{2}(x)}{x_{1}(x)} \ge \frac{1}{2} \frac{y_{2}(x_{1})}{x_{2}(x)} \\ \end{bmatrix}$$

$$\begin{pmatrix} e \end{pmatrix} Let \begin{bmatrix} y_{n} = x_{n-n}, \\ \frac{1}{2} \frac{y_{2}(x_{2})}{x_{2}(x)} \ge \frac{1}{2} \frac{y_{2}(x_{1})}{x_{2}(x)} \\ = E \begin{bmatrix} x_{n-n}, x_{n+n-n} \end{bmatrix} \\ = \frac{g_{2}(x_{1})}{2} \\ Obviously \begin{bmatrix} \frac{1}{2} \frac{y_{2}(x_{1})}{x_{2}(x)} = \frac{1}{2} \frac{y_{2}}{x_{2}(x)} \\ f_{x_{2}}(x) \ge \frac{1}{x_{2}(x)} \\ \end{bmatrix}$$

$$\begin{pmatrix} f \end{pmatrix} Let \begin{bmatrix} y_{x_{1}}(x) \Longrightarrow \int_{x_{2}(x)} \frac{1}{x_{2}(x)} \\ f_{x_{2}}(x) \ge \frac{1}{x_{2}(x)} \\ f_{x_{2}}(x) \ge \frac{1}{x_{2}(x)} \\ \end{bmatrix}$$

$$\begin{pmatrix} f \end{pmatrix} Let \begin{bmatrix} y_{x_{2}}(x_{1}) \Longrightarrow \int_{x_{2}(x)} \frac{1}{x_{2}(x)} \\ f_{x_{2}}(x) \ge \frac{1}{x_{2}(x)} \\ f_{x_{2}}(x) \ge \frac{1}{x_{2}(x)} \\ \end{bmatrix}$$

$$\begin{pmatrix} f \end{pmatrix} Let \begin{bmatrix} y_{x_{2}}(x_{1}) \Longrightarrow \int_{x_{2}(x)} \frac{1}{x_{2}(x)} \\ f_{x_{2}}(x) \ge \frac{1}{x_{2}(x)} \\ f_{x_{2}}(x) \ge \frac{1}{x_{2}(x)} \\ f_{x_{2}}(x) \ge \frac{1}{x_{2}(x)} \\ f_{x_{2}}(x) \ge \frac{1}{x_{2}(x)} \\ f_{x_{2}}(x_{2}) = \frac{1}{x_{2}(x)} \\ f_{x_{2}}(x_{2}) = \frac{1}{x_{2}(x$$

$$\mathcal{U}_{M} \quad Y_{xy}(m) = Y_{yx}^{\#}(-m)$$

$$\Gamma_{xy}(z) = \sum_{m_{2-\infty}}^{\infty} Y_{xy}(m) z^{m} = \sum_{m_{2-\infty}}^{\infty} Y_{yx}^{\#}(-m) z^{m}$$

$$= \left(\sum_{\ell=-\infty}^{\infty} Y_{yx}(\ell) (z^{\ell})^{-\ell}\right)^{\#} = \Gamma_{yx}^{\#}(l)/z^{\mu}$$

$$= \left(\sum_{\ell=-\infty}^{\infty} Y_{yx}(\ell) (z^{\ell-1})^{-\ell}\right)^{\#} = \Gamma_{yx}^{\#}(l)/z^{\mu}$$

### 4.3 HW4, Some floating points computation

#### Local contents

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#### 4.3.1 my solution, First Problem

Looking at 2 floating points problems. The first to illustrate the problem when adding large number to small number. The second to illustrate the problem of subtracting 2 numbers close to each others in magnitude.

Investigate floating point errors generated by the following sum  $\sum_{n=1}^{N} \frac{1}{n^2}$ , compare the result to that due summation in forward and in reverse directions.

#### 4.3.1.1 Analysis

When performing the sum in the forward direction, as in  $1 + \frac{1}{4} + \frac{1}{16} + \cdots + \frac{1}{N^2}$  we observe that very quickly into the sum, we will be adding relatively large quantity to a very small quantity. Adding a large number of a very small number leads to loss of digits as was discussed in last lecture. However, we adding in reverse order, as in  $\frac{1}{N^2} + \frac{1}{(N-1)^2} + \frac{1}{(N-2)^2} + \cdots + 1$ , we see that we will be adding, each time, 2 quantities that are relatively close to each other in magnitude. This reduces floating point errors.

The following code and results generated confirms the above. N = 20,000 was used. The computation was forced to be in single precision to be able to better illustrate the problem.

#### 4.3.1.2 Computation and Results

This program prints the result of the sum in the forward direction

```
PROGRAM main
1
          IMPLICIT NONE
\mathbf{2}
          REAL :: s
3
          INTEGER :: n,MAX
4
5
          s = 0.0;
6
          MAX = 20000;
7
          DO n = 1, MAX
8
9
             s = s + (1./n**2);
          END DO
10
11
          WRITE(*,1) s
12
          format('sum = ', F8.6)
13
   1
          END PROGRAM main
14
15
16
17
   sum = 1.644725
```

now compare the above result with that when performing the sum in the reverse direction

```
PROGRAM main
1
          IMPLICIT NONE
\mathbf{2}
          REAL :: s
3
          INTEGER :: n,MAX
4
5
          s = 0.0;
6
          MAX = 20000;
7
          DO n = MAX, 1, -1
8
             s = s + (1./n**2);
9
          END DO
10
11
          WRITE(*,1) s
12
13 1
          format('sum = ', F8.6)
```

| 14 | END PROGRAM main |
|----|------------------|
| 15 |                  |
| 16 | sum = 1.644884   |

The result from the reverse direction sum is the more accurate result. To proof this, we can use double precision and will see that the sum resulting from double precision agrees with the digits from the above result when using reverse direction sum

```
PROGRAM main
 1
          IMPLICIT NONE
2
          DOUBLE PRECISION :: s
\mathbf{3}
4
          INTEGER :: n,MAX
5
\mathbf{6}
          s = 0.0;
          MAX = 20000;
7
          DO n = 1, MAX
 8
             s = s + (1./n**2);
9
          END DO
10
11
12
          WRITE(*,1) s
          format('sum = ', F18.16)
13
   1
          END PROGRAM main
14
15
   sum = 1.6448840680982091
16
```

#### 4.3.1.3 Conclusion

In floating point arithmetic, avoid adding a large number to a very small number as this results in loss of digits of the small number. The above trick illustrate one way to accomplish this and still perform the required computation.

In the above, there was  $1.644884 - 1.644725 = 1.59 \times 10^{-4}$  error in the sum when it was done in the forward direction as compared to the reverse direction (for 20,000 steps). In relative term, this error is  $\frac{1.644884 - 1.644725}{1.644884}$  100 which is about 0.01% relative error.

#### 4.3.2 my solution, second problem

Investigate the problem when subtracting 2 numbers which are close in magnitude. If a, b are 2 numbers close to each others, then instead of doing a - b do the following  $(a - b)\frac{(a+b)}{(a+b)} = \frac{a^2-b^2}{a+b}$ . The following program attempts to illustrate this by comparing

result from a - b to that from  $\frac{a^2 - b^2}{a + b}$  for 2 numbers close to each others.

```
PROGRAM main
1
          IMPLICIT NONE
2
         DOUBLE PRECISION :: a,b,diff
3
4
         a = 32.000008;
5
         b = 32.000002;
6
          diff = a-b;
\overline{7}
         WRITE(*,1), diff
8
          diff = (a**2-b**2)/(a+b);
9
          WRITE(*,1), diff
10
11
   1
          format('diff = ', F18.16)
          END PROGRAM main
12
13
   diff = 0.0000038146972656
14
   diff = 0.0000038146972656
15
```

I need to look more into this as I am not getting the right 2 numbers to show this problem.

## 4.3.3 key solution

$$\frac{Sol, H.W. 4}{Y(h-1) + X(h)}$$

$$\frac{9-6}{Y(h) = \ll Y(h-1) + X(h)}$$

$$variables & coefficients : sign - & -magnitude results of mult.'s : truncated
$$\Rightarrow W(h) = Q [ \ll W(h-1)] + X(h)$$

$$Q [.] : Nign - & -mag. truncation.$$

$$possibility of a zero-input limit cycle
$$[W(h)] = [W(h-1)] \quad \forall n$$

$$s how that if the ideal sys. is stable, then no zero - input limit cycle can exist. Is the Name true for 2's complement truncation?
$$\frac{Sol.}{To have zero-input limit cycle}$$

$$[W(h)] = [W(h-1)] = [W(h-1)] \quad (1)$$

$$s table sys. => |\alpha| < 1$$

$$\Rightarrow | \ll W(h-1) | < |W(h-1)| \quad (2)$$

$$a) \quad For Nigh - & -mag. truncation.$$

$$-2^{-b} < Q(x) - x \leq 0 \qquad X \ge 0$$

$$0 \leq Q(x) - x < 2^{-b} \qquad X(0)$$$$$$$$

$$\Rightarrow |Q(x)| \leq |x| \quad \text{for } x \geq 0 \text{ or } x < 0$$
Let  $x = x W(n-1)$ 

$$\Rightarrow |Q[xw(n-1)]| \leq |xw(n-1)| \quad (3)$$
(3)  $4(z) \Rightarrow |Q[xw(n-1)]| \leq |xw(n-1)| \quad (3)$ 
(3)  $4(z) \Rightarrow |Q[xw(n-1)]| \leq |xw(n-1)| < |w(n-1)|$ 
Since (1) is not ratiofied magers imput  
limit cycle is possible.  
b) For  $Q[z] = two's complement$ 

$$-z^{-b} \leq Q(x) - x \leq 0 \quad \forall \neq$$

$$Ip \quad \underline{x} \geq 0 \quad x \geq Q[x] \quad \text{or } |x| \geq |Q[x]| \quad (4)$$

$$Ip \quad \underline{x} < 0 \quad |Q[x|| \geq |x|] \quad (5) \quad \forall$$
For  $x W(n-1) \geq 0$ 

$$|Q[xw(n-1)]| \leq |xw(n-1)| \leq |w(n-1)|$$

$$\oplus mo \ limit Cycle \quad : (1) is not ratiofied$$
For  $x W(n-1) < 0$ 

$$|xw(n-1)| \leq |R[xw(n-1)]| \quad ling (5)$$

$$and |xw(n-1)| < |w(n-1)| \quad ling (5)$$

$$Possible that \quad |Q[xw(n-1)] = |w(n-1)| \quad for$$

$$xW(n-1) < 0 \quad \Rightarrow \ limit cycle$$

| •       | 9-7 ×(n) 3/1  |
|---------|---|
| 7       | QL] (m)   |
| C       | QE]: rounding   |
|         | Fixed-pt. fractions, b lits   |
|         | zero input - Y(-1) = A initial cond.  |
|         | Dead hand: A >   R [ ~ A]   = A   |
|         | a) dead hand in terms of & and B  |
|         | b) For b=6, A=1/16 sketch Yini for x= { 15/16                                 |
|         | () For b=6, A=1/2 shotch Vini lan in - 15/16                                  |
|         | 50/1  |
| fur.    | $Y(h) = Q \left[ \alpha Y(h-1) \right] + X(h) \qquad (X(h) = 0)$              |
|         | Rounding: $-\frac{z^{-b}}{z} < R [q W(h-1)] - q W(h-1) \leq \frac{z^{-b}}{z}$ |
|         | If filter is in the dead hand   |
|         | $-\frac{z^{-b}}{z} < Q [aA] - aA < \frac{z^{-b}}{z}$                          |
|         | or $ Q[rA] - rA  \leq \frac{2-b}{2}$  |
|         | In a limit Cycle (REMA] = A   |
|         | => $ QEAI  -  AA  \leq  REAI - AA  \leq \frac{1}{2} z^{-b}$                   |
| (inter- | $\Rightarrow$ $ A  -  x  A  < \frac{1}{2} 2^{-b}$                             |
|         | <b>~</b>  |

$$= (A) \leq \frac{\frac{1}{2}}{1-1<1}$$

$$b) = 6 = 2^{-b} = 1/64 \quad |\kappa| = \frac{15}{16} \quad 1-14| = \frac{1}{16}$$

$$1A1 \leq \frac{\frac{1}{2} \cdot \frac{1}{64}}{\frac{1}{15}} = \frac{1}{8} \quad \frac{dead \ hand}{1}$$

$$Thus for \quad A = \frac{1}{16} \quad the system starts immediately in the limit cycle.$$

$$a = \frac{15}{16} \quad Y(n) = Q \quad [\kappa \quad Y(n-n)] = Q \quad [\frac{15}{16} \cdot \frac{1}{16}] = Q \quad [\frac{15}{256}] = \frac{1}{16}$$

$$\frac{1}{16} \quad Y(n) = Q \quad [-\frac{15}{16} \cdot \frac{1}{16}] = \begin{cases} -\frac{1}{16} & n \text{ even} \end{cases}$$

$$\frac{1}{16} \quad \frac{1}{16} \quad n \text{ odd}$$

$$\frac{1}{16} \quad \frac{1}{16} \quad \frac{1}{16} \quad n \text{ odd}$$

$$\frac{1}{16} \quad \frac{1}{16} \quad \frac{1}{16} \quad n \text{ odd}$$

$$\frac{1}{16} \quad \frac{1}{16} \quad \frac{1}{$$





$$\frac{||.1|}{C_{xx}(m)} = \frac{1}{N} \sum_{\substack{N=1 \text{ min} - 1 \\ N=0}}^{N-1 \text{ min} - 1} \frac{\sum_{\substack{X \in N \mid X(n+m) \\ X(n) \neq N(n) \neq N-1}}^{N-1 \text{ min} |X(n+m)} \frac{||m| \leq N-1}{||m| \leq N-1|}$$

$$\frac{||N|(w) = \frac{1}{N} |X(e^{jw})|^2 \sum_{\substack{N=1 \\ N=0}}^{N-1} \sum_{\substack{X \in N \mid Y \neq X(n) \neq N-1}}^{N-1} \frac{||m| \leq N-1}{|N|} \sum_{\substack{X \in N \mid Y \neq X(n) \neq X(n) \neq N-1}}^{N-1} \frac{||m| \leq N-1}{|N|} \sum_{\substack{X \in N \mid Y \neq X(n) \neq X(n) \neq X(n) \neq X(n) \neq N-1}}^{N-1} \frac{||m| \leq N-1}{|N|} \sum_{\substack{X \in N \mid Y \neq X(n) = \frac{1}{N} |X(e^{jw})|^2$$

$$\frac{\sigma_{1}}{\sum_{\substack{M=-(W+1) \\ M=-(W+1) \neq X(n) = \frac{1}{N} \sum_{\substack{X \in N \mid X \mid X(n) \neq X(n) = \frac{1}{N} \sum_{\substack{X = N \mid X \mid X \mid X(n) \neq X(n) = \frac{1}{N} \sum_{\substack{X = N \mid X \mid X \mid X \mid X(n) \neq X(n) = \frac{1}{N} \sum_{\substack{X = N \mid X \mid X \mid X \mid X \mid X \mid X(n) \neq X(n$$

$$I_{N}(\omega) = \frac{1}{N} \left[ \sum_{n=0}^{N-1} x(n) e^{-j\omega h} \int_{t=0}^{t} \frac{N-1}{t=0} x(t) e^{-j\omega t} \right]$$

$$= \frac{1}{N} \left| X(e^{j\omega}) \right|^{2}$$

$$\frac{11.2}{M} \sum_{x_{x}(\omega)} \sum_{m=-(M-1)}^{M-1} C_{x_{x}}(m) W(m) e^{-j\omega m}$$

$$W(m) \text{ of langth } 2M-1$$

$$\frac{1}{N \log t hat} E \left\{ S_{x_{x}(\omega)} \right\} = \frac{1}{2\pi} \int_{-\pi}^{\pi} E \left\{ I_{N}(\theta) \right\} W(e^{j(\omega-\theta)}) d\theta$$

$$\begin{cases} W(m) = 0 \quad |m| \ge 2M \\ C_{x_{x}}(m) = 0 \quad for \ |m| \ge M \\ C_{x_{x}}(m) = 0 \quad for \ |m| \ge M \\ K nowing these \ we \ con \ hay$$

$$S_{x_{x}}(\omega) = \sum_{m=-\infty}^{\infty} C_{x_{x}}(m) W(m) e^{-j\omega m}$$

$$= \sum_{m=-\infty}^{\infty} \left\{ C_{x_{x}}(m) W(m) e^{-j\omega m} \right\}$$

$$= \frac{1}{2\pi} \int_{-\pi}^{\pi} \neq \left\{ C_{x_{x}}(m) \right\} W(e^{j(\omega-\theta)}) d\theta \quad cow$$

$$= \frac{1}{2\pi} \int_{-\pi}^{\pi} I_{N}(\theta) \ W(e^{j(\omega-\theta)}) d\theta$$

$$E \left\{ S_{xx}(\omega) \right\} = \frac{1}{2\pi} \int_{-\pi}^{\pi} E \left\{ I_{N}(\theta) \right\} W(e^{j(\omega-\theta)}) d\theta$$

### 4.4 HW5

#### Local contents

| 4.4.1 | Problem 11.1 | <br> |  |  |   | <br>• |   |   |   |  |   |  |  |   |   |   | • |  |   | 40 |
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| 4.4.2 | Problem 11-2 | <br> |  |  | • | <br>• | • | • | • |  | • |  |  | • | • | • | • |  | • | 41 |

#### 4.4.1 Problem 11.1

1. Let  $X(e^{i\omega})$  be the Fourier transform of a real finite-length sequence x(n) that is zero outside the interval  $0 \le n \le N - 1$ . The periodogram  $I_N(\omega)$  is defined in Eq. (11.24) as the Fourier transform of the 2N - 1 point autocorrelation estimate  $c_{xx}(m) = \frac{1}{N} \sum_{n=0}^{N-|m|-1} x(n)x(n+m) \qquad |m| \le N - 1.$ 

Show that the periodogram is related to the Fourier transform of the finite length sequence as follows: 1

$$I_N(\omega) = \frac{1}{N} |X(e^{j\omega})|^2.$$

Figure 4.2: the Problem statement

$$I_{N}(\omega) = \sum_{m=-(N-1)}^{N-1} c_{xx}(m) e^{-j\omega m}$$

$$\begin{split} \left| X\left(e^{j\omega}\right) \right|^2 &= X\left(e^{j\omega}\right) X^*\left(e^{j\omega}\right) \\ &= \left(\sum_{m=0}^{N-1} x\left(m\right) e^{-j\omega m}\right) \left(\sum_{n=0}^{N-1} x\left(n\right) e^{-j\omega n}\right)^* \\ &= \left(\sum_{m=0}^{N-1} x\left(m\right) e^{-j\omega m}\right) \left(\sum_{n=0}^{N-1} x^*\left(n\right) e^{j\omega n}\right) \\ &= \sum_{m=0}^{N-1} \sum_{n=0}^{N-1} x\left(m\right) x^*\left(n\right) e^{-j\omega m} e^{j\omega n} \end{split}$$

But

$$e^{-j\omega m}e^{j\omega n} = e^{-j\omega(m-n)}$$

and

$$x(m) x^{*}(n) = x(m) x^{*}(m + (n - m))$$

 $\operatorname{So}$ 

$$\left| X\left( e^{j\omega} \right) \right|^2 = \sum_{m=0}^{N-1} \sum_{n=0}^{N-1} x\left( m \right) x^* \left( m + (n-m) \right) e^{-j\omega(m-n)}$$

Let  $n - m = \tau$  then above can be rewritten as

$$\left|X\left(e^{j\omega}\right)\right|^{2} = \sum_{m=0}^{N-1} \sum_{n=0}^{N-1} x(m) x^{*}(m+\tau) e^{j\omega\tau}$$

When  $n = 0, m = -\tau$  and when  $n = N - 1, m = N - \tau - 1$ , hence the above becomes

$$\left| X\left(e^{j\omega}\right) \right|^{2} = \sum_{m=0}^{N-1} \sum_{m=-\tau}^{N-\tau-1} x\left(m\right) x^{*}\left(m+\tau\right) e^{j\omega\tau} = \sum_{m=0}^{N-1} \left( \sum_{m=-\tau}^{-1} x\left(m\right) x^{*}\left(m+\tau\right) e^{j\omega\tau} + \sum_{m=0}^{N-|\tau|-1} x\left(m\right) x^{*}\left(m+\tau\right) e^{j\omega\tau} \right) = \sum_{m=0}^{N-1} \left( \sum_{m=-1}^{-\tau} x\left(m\right) x^{*}\left(m+\tau\right) e^{j\omega\tau} + N c_{xx}\left(m\right) e^{j\omega\tau} \right)$$

I made another attempt at the end,

#### 4.4.2 Problem 11-2

2. The smoothed spectrum estimate  $S_{xx}(\omega)$  is defined as  $S_{xx}(\omega) = \sum_{m=-(M-1)}^{M-1} c_{xx}(m)w(m)e^{-j\omega m},$ where w(m) is a window sequence of length 2M - 1. Show that  $E[S_{xx}(\omega)] = \frac{1}{2\pi} \int_{-\pi}^{\pi} E[I_N(\theta)]W(e^{i(\omega-\theta)}) d\theta,$ where  $W(e^{j\omega})$  is the Fourier transform of w(n).

Figure 4.3: the Problem statement

We see that  $S_{xx}(\omega)$  is the Fourier transform of  $c_{xx}(m) w(m)$ . i.e.

$$S_{xx}\left(\omega\right) = F\left[c_{xx}\left(m\right)w\left(m\right)\right]$$

Where F is the Fourier transform operator. Using modulation property

$$S_{xx}(\omega) = \frac{1}{2\pi} \left( F\left[ c_{xx}(m) \right] \otimes F\left[ w\left( m \right) \right] \right)$$

But  $I_{N}(\omega) = F[c_{xx}(m)]$  and let  $W(\omega) = F[w(m)]$ , then the above becomes

$$S_{xx}(\omega) = \frac{1}{2\pi} \left( I_N(\omega) \otimes W(\omega) \right)$$
$$= \frac{1}{2\pi} \int_{-\pi}^{\pi} I_N(\theta) W(\omega - \theta) \, d\theta$$

Hence, taking expectation of LHS, and since only  $I_N(\theta)$  is random, then the above becomes (after moving expectation inside the integral in the RHS)

$$E\left[S_{xx}\left(\omega\right)\right] = \frac{1}{2\pi} \int_{-\pi}^{\pi} E\left[I_{N}\left(\theta\right)\right] W\left(\omega - \theta\right) d\theta$$