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HW # 6

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MAE 200A.

Nov 1, 2005

$$\ddot{x} + 2\zeta\omega_n \dot{x} + \omega_n^2 x = 0$$

①

let  $x_1 = x$

$x_2 = \dot{x}$

hence we set 
$$\begin{pmatrix} \dot{x}_1 \\ \dot{x}_2 \end{pmatrix} = \underbrace{\begin{pmatrix} 0 & 1 \\ -\omega_n^2 & -2\zeta\omega_n \end{pmatrix}}_A \begin{pmatrix} x_1 \\ x_2 \end{pmatrix}$$

Case 1  $\omega = 1, \zeta = 5$

$A = \begin{pmatrix} 0 & 1 \\ -1 & -10 \end{pmatrix}$  here Eigenvalues  $|A - \lambda I| = 0 \Rightarrow$

$$\begin{vmatrix} -\lambda & 1 \\ -1 & -10-\lambda \end{vmatrix} = 0 \Rightarrow \lambda^2 + 10\lambda + 1 = 0 \Rightarrow \begin{cases} \lambda_1 = -5 + 2\sqrt{6} \\ \lambda_2 = -5 - 2\sqrt{6} \end{cases}$$

To find eigenvectors we can solve  $Av = \lambda v$ .

but since  $\lambda$ 's are distinct, then Jordan form is

$$\begin{pmatrix} \lambda_1 & 0 \\ 0 & \lambda_2 \end{pmatrix}$$

hence an alternative ODE form is similarity transformation:

$$\dot{\bar{z}} = (P^{-1}AP) \bar{z}$$

but  $P^{-1}AP = \begin{pmatrix} \lambda_1 & 0 \\ 0 & \lambda_2 \end{pmatrix}$

$\bar{z} = P^{-1}x$

hence 
$$\dot{\bar{z}} = \begin{pmatrix} \lambda_1 & 0 \\ 0 & \lambda_2 \end{pmatrix} \bar{z}$$

∴ 
$$\begin{pmatrix} \dot{z}_1 \\ \dot{z}_2 \end{pmatrix} = \begin{pmatrix} -5+2\sqrt{6} & 0 \\ 0 & -5-2\sqrt{6} \end{pmatrix} \begin{pmatrix} z_1 \\ z_2 \end{pmatrix}$$

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Case 2  $\omega_n = 1$ ,  $\xi = 1$

(2)

$$A = \begin{pmatrix} 0 & 1 \\ -1 & -2 \end{pmatrix}, \Rightarrow |A - \lambda I| = 0.$$

$$\begin{vmatrix} -\lambda & 1 \\ -1 & -2-\lambda \end{vmatrix} = 0 \Rightarrow -\lambda(-2-\lambda) + 1 = 0 \Rightarrow \lambda = -1, -1.$$

since duplicate eigenvalue, the possible form for Jordan form is  $\begin{pmatrix} \lambda & 1 \\ 0 & \lambda \end{pmatrix}$ .

generalized eigenvector?

$$\dot{z} = \begin{pmatrix} -1 & 1 \\ 0 & -1 \end{pmatrix} z \Rightarrow$$

$$\begin{pmatrix} \dot{z}_1 \\ \dot{z}_2 \end{pmatrix} = \begin{pmatrix} -1 & 1 \\ 0 & -1 \end{pmatrix} \begin{pmatrix} z_1 \\ z_2 \end{pmatrix}$$

$\bar{z} = ? \mathbb{R}$

Case 3  $\omega_n = 1$ ,  $\xi = 0.5$

$$A = \begin{pmatrix} 0 & 1 \\ -1 & -1 \end{pmatrix} \Rightarrow A - \lambda I = \det \begin{pmatrix} -\lambda & 1 \\ -1 & -1-\lambda \end{pmatrix} = 0$$

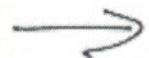
$$\Rightarrow -\lambda(-1-\lambda) + 1 = 0 \Rightarrow \lambda^2 + \lambda + 1 = 0 \Rightarrow \lambda = \frac{-1 \pm \sqrt{1-4}}{2}$$

$$\lambda = -\frac{1}{2} \pm j\frac{\sqrt{3}}{2}$$

ie  $\lambda = \sigma \pm j\omega$  where  $\alpha = -\frac{1}{2}$ ,  $\omega = \frac{\sqrt{3}}{2}$

then Jordan Form is  $\begin{pmatrix} \sigma & -\omega \\ \omega & \sigma \end{pmatrix} = \begin{pmatrix} -\frac{1}{2} & -\frac{\sqrt{3}}{2} \\ \frac{\sqrt{3}}{2} & -\frac{1}{2} \end{pmatrix}$

$$\dot{z} = \begin{pmatrix} \dot{z}_1 \\ \dot{z}_2 \end{pmatrix} = \begin{pmatrix} -\frac{1}{2} & -\frac{\sqrt{3}}{2} \\ \frac{\sqrt{3}}{2} & -\frac{1}{2} \end{pmatrix} \begin{pmatrix} z_1 \\ z_2 \end{pmatrix}$$



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2 distinct eigenvalues  $\lambda_1 = -1 + j\frac{\sqrt{3}}{2}$ ,  $\lambda_2 = -1 - j\frac{\sqrt{3}}{2}$ .

so Jordan Form  $\begin{pmatrix} \lambda_1 & 0 \\ 0 & \lambda_2 \end{pmatrix} \Rightarrow$

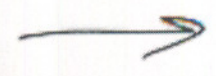
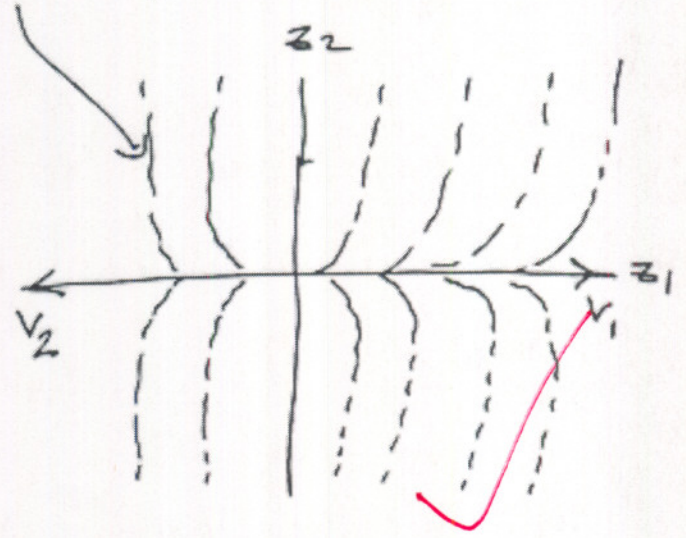
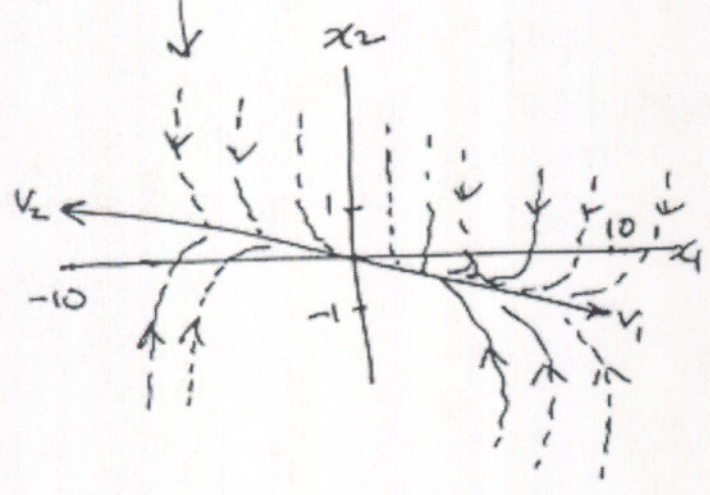
$$\begin{pmatrix} \dot{z}_1 \\ \dot{z}_2 \end{pmatrix} = \begin{pmatrix} -1 + j\frac{\sqrt{3}}{2} & 0 \\ 0 & -1 - j\frac{\sqrt{3}}{2} \end{pmatrix} \begin{pmatrix} z_1 \\ z_2 \end{pmatrix}$$

~~use~~  
how about real matrix  $\begin{bmatrix} \sigma & w \\ w & \sigma \end{bmatrix}$

sketch of state portrait

(p.s. For this part I used matlab to help find eigenvectors  $[v, d] = \text{eig}(A)$ )

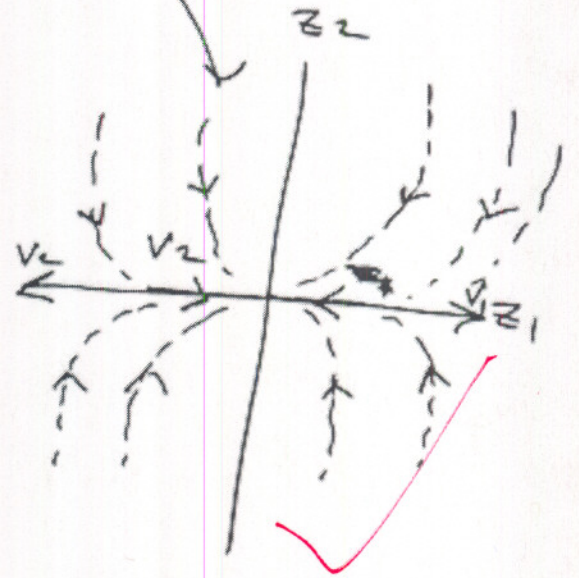
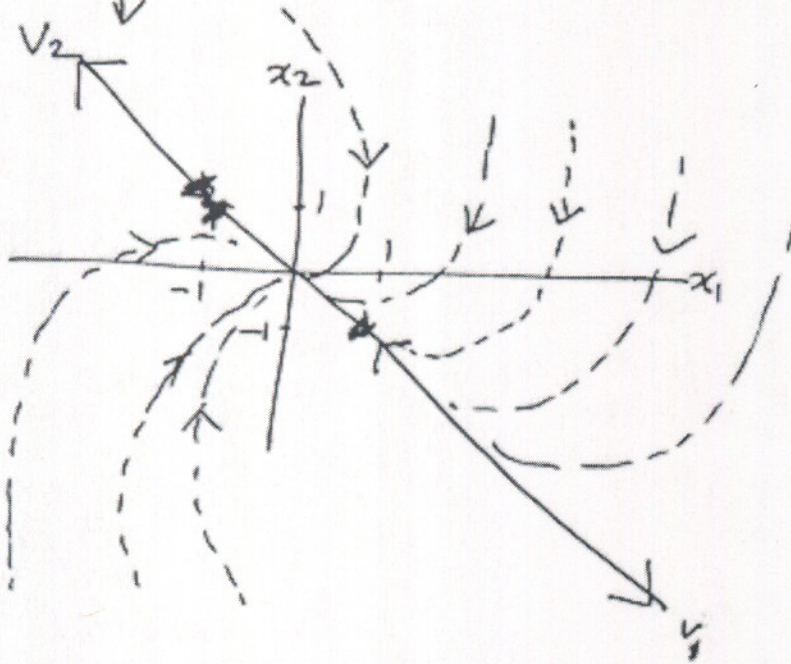
Case 1 original rep.  $\dot{x} = \begin{pmatrix} 0 & 1 \\ -1 & -10 \end{pmatrix} x$   
modified rep.  $\dot{z} = \begin{pmatrix} -5 + 2\sqrt{6} & 0 \\ 0 & -5 - 2\sqrt{6} \end{pmatrix} z$



Case 2

original  $\dot{x} = \begin{pmatrix} 0 & 1 \\ -1 & -2 \end{pmatrix} x$

transformed  $\dot{z} = \begin{pmatrix} -1 & 1 \\ 0 & -1 \end{pmatrix} z$



Case 3

original  $\dot{x} = \begin{pmatrix} 0 & 1 \\ -1 & -1 \end{pmatrix} x$

modified  $\dot{z} = \begin{pmatrix} -1 + j\frac{\sqrt{2}}{2} & 0 \\ 0 & -1 - j\frac{\sqrt{2}}{2} \end{pmatrix} z$

