

Basic Tikz examples

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All the tikz examples I see on the net are too complicated to learn from, so I am making simple ones to help me learn from.

To draw x,y coordinates system

```
\begin{tikzpicture}
\draw (0,0) -- (1,0);
\draw (0,0) -- (0,1);
\end{tikzpicture}
```



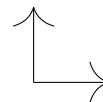
To make the x,y axis arrows

```
\begin{tikzpicture}
\draw[->] (0,0) -- (1,0);
\draw[->] (0,0) -- (0,1);
\end{tikzpicture}
```



To make the arrow heads larger (needs `arrows.meta`)

```
\begin{tikzpicture}
\draw[->[scale=3.0]] (0,0) -- (1,0);
\draw[->[scale=3.0]] (0,0) -- (0,1);
\end{tikzpicture}
```



To make the arrow heads solid

```
\begin{tikzpicture}
\draw[-{Latex[scale=2.0]}] (0,0) -- (1,0);
\draw[-{Latex[scale=2.0]}] (0,0) -- (0,1);
\end{tikzpicture}
```



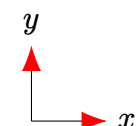
To make the axis red colored

```
\begin{tikzpicture}
\draw[-{Latex[red,scale=2.0]}] (0,0) -- (1,0);
\draw[-{Latex[red,scale=2.0]}] (0,0) -- (0,1);
\end{tikzpicture}
```



To add labels on axis

```
\begin{tikzpicture}
\draw[-{Latex[red,scale=2.0]}] (0,0) -- (1,0) node [right] {
  $x$};
\draw[-{Latex[red,scale=2.0]}] (0,0) -- (0,1) node [above] {
  $y$};
\end{tikzpicture}
```

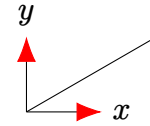


To draw line at 30 degrees of length 2 unit using cartesian coordinates

```

\begin{tikzpicture}
\draw[-{Latex[red,scale=2.0]}] (0,0) -- (1,0) node [right] {
  $x$};
\draw[-{Latex[red,scale=2.0]}] (0,0) -- (0,1) node [above] {
  $y$};
\draw (0,0) -- ({2*cos(30)},{2*sin(30)});
\end{tikzpicture}

```

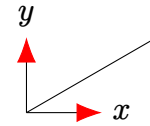


To defined the line length as variable

```

\begin{tikzpicture}
\draw[-{Latex[red,scale=2.0]}] (0,0) -- (1,0) node [right] {
  $x$};
\draw[-{Latex[red,scale=2.0]}] (0,0) -- (0,1) node [above] {
  $y$};
\draw let \n1={2} in (0,0) -- ({\n1*cos(30)},{\n1*sin(30)});
\end{tikzpicture}

```

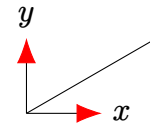


To use polar coordinates to draw the line

```

\begin{tikzpicture}
\draw[-{Latex[red,scale=2.0]}] (0,0) -- (1,0) node [right] {
  $x$};
\draw[-{Latex[red,scale=2.0]}] (0,0) -- (0,1) node [above] {
  $y$};
\draw let \n1={2} in (0,0) -- (30:\n1);
\end{tikzpicture}

```

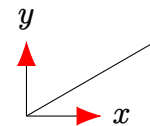


To define the length of the line using the new evaluate

```

\begin{tikzpicture}
\draw[-{Latex[red,scale=2.0]}] (0,0) -- (1,0) node [right] {
  $x$};
\draw[-{Latex[red,scale=2.0]}] (0,0) -- (0,1) node [above] {
  $y$};
\draw[evaluate={\r1=2;}] (0,0) -- (30:\r1);
\end{tikzpicture}

```

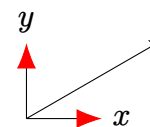


To make the line an arrow

```

\begin{tikzpicture}
\draw[-{Latex[red,scale=2.0]}] (0,0) -- (1,0) node [right] {
  $x$};
\draw[-{Latex[red,scale=2.0]}] (0,0) -- (0,1) node [above] {
  $y$};
\draw[->,evaluate={\r1=2;}] (0,0) -- (30:\r1);
\end{tikzpicture}

```

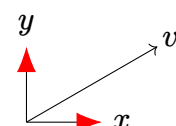


To put label at end of line

```

\begin{tikzpicture}
\draw[-{Latex[red,scale=2.0]}] (0,0) -- (1,0) node [right] {
  $x$};
\draw[-{Latex[red,scale=2.0]}] (0,0) -- (0,1) node [above] {
  $y$};
\draw[->,evaluate={\r1=2;}] (0,0) -- (30:\r1) node [pos=1.1] {
  $v$};
\end{tikzpicture}

```



Make a 2 link RR robot arm

```

\def\L{1}
\def\w{\L/2}
\begin{tikzpicture}
%bottom link
\draw ({-\w/2},0) -- ({\w/2},0) -- ({\w/2},\L) -- ({-\w/2},\L)
      --cycle;
\draw ({\w/2},\L) arc (0:180:{\w/2});
%top link
\draw [shift={(0,{\L+\w/3})},rotate=45] ({\w/4},0) arc
      (0:-180:{\w/4});
\draw [shift={(0,{\L+\w/3})},rotate=45] ({\w/4},0) -- ({\w/4},\L)
      -- ({-\w/4},\L) -- ({-\w/4},0) --cycle;
\end{tikzpicture}

```

